

Matchings under Preferences: Strength of Stability and Trade-Offs

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University of Warsaw



Stable Matchings

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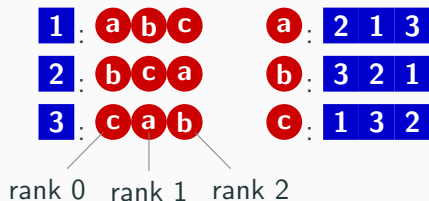
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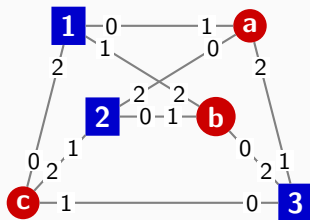
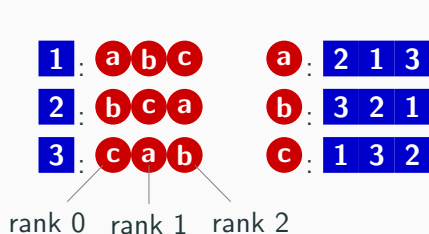


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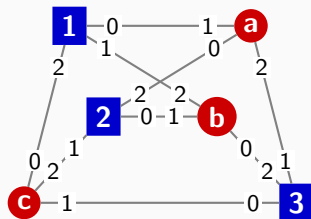
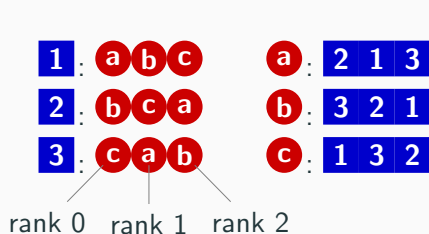


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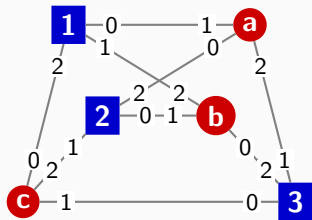
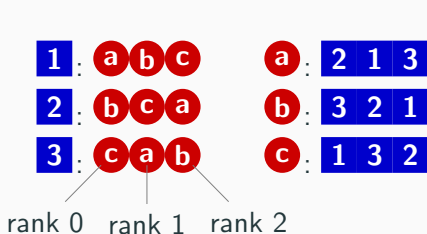
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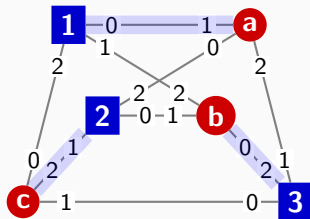
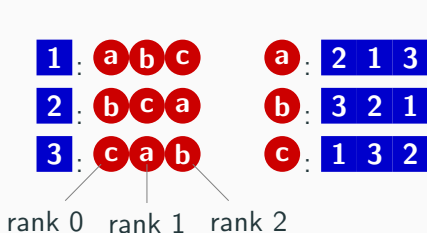
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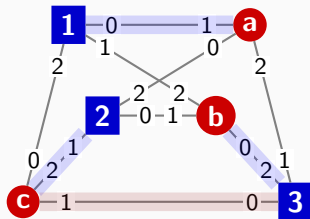
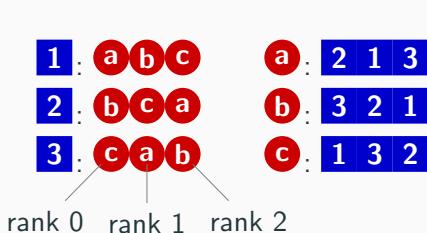
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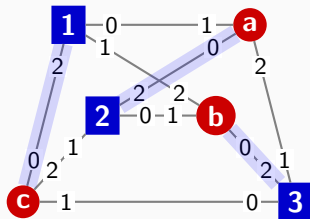
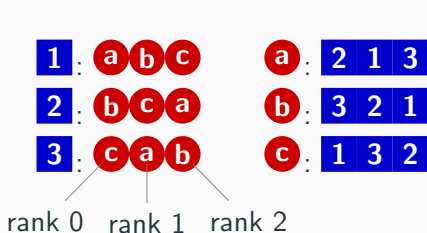
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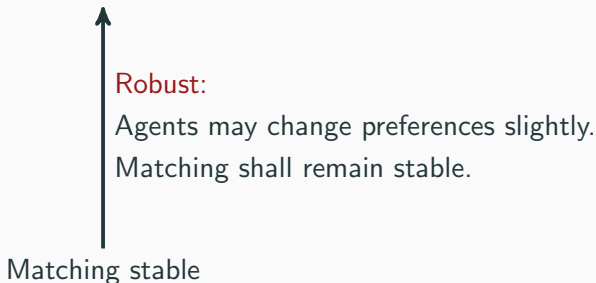
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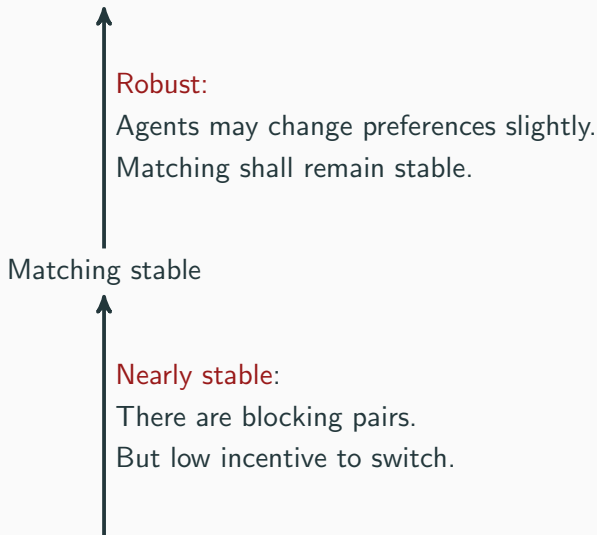
Stability: Qualitative vs. Quantitative

Matching stable

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↪ **Aim:** Stable matching in all **nearby** profiles

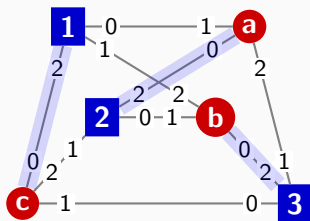
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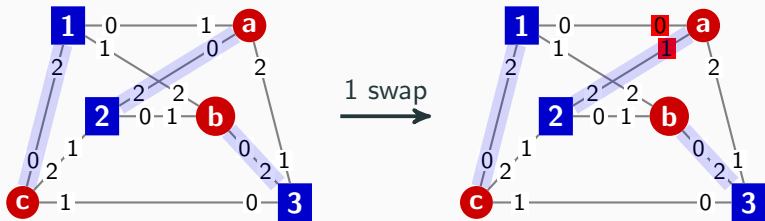
Definition (Robust Matching)

Let $d \in \mathbb{N}$. A matching M for a profile P is **d -robust** if M is stable in each profile Q that is at most d swaps away from P .

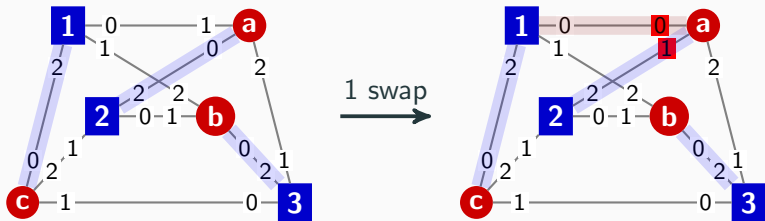
Robustness: Example



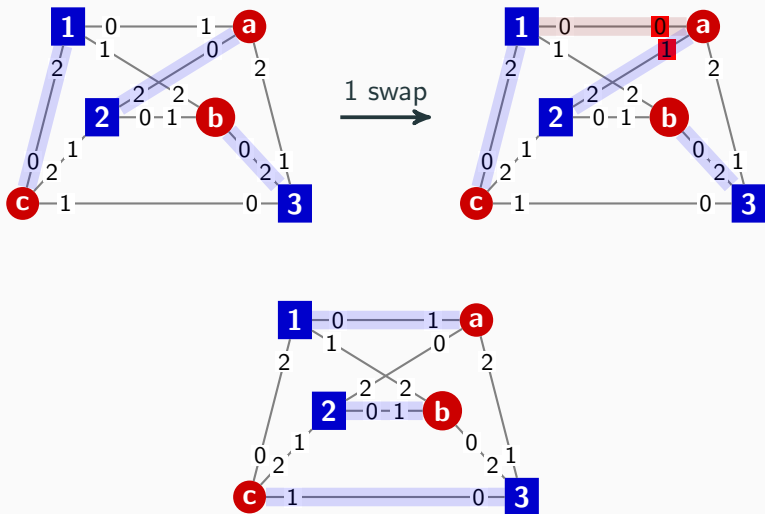
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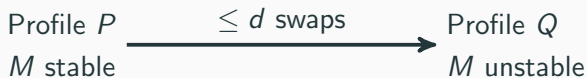
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- $O(n^d)$ profiles $\rightsquigarrow O(n^4)$ **critical** profiles
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- Find closed subset of rotations in modified rotation poset

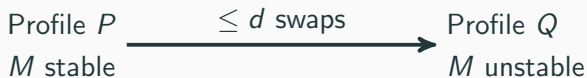
Critical Profiles

Fix matching M that is not d -robust.



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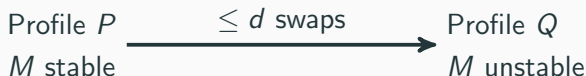
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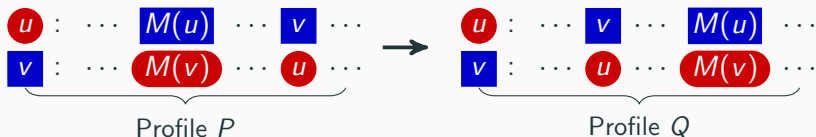
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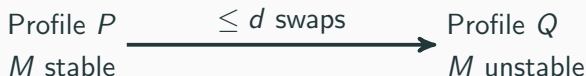


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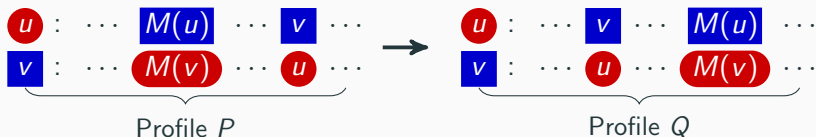


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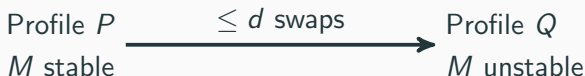
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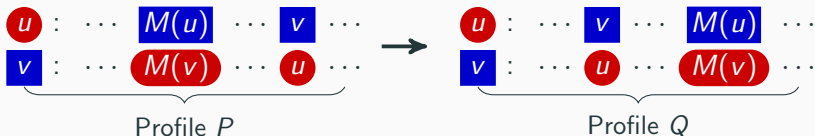
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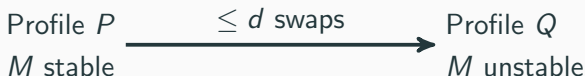


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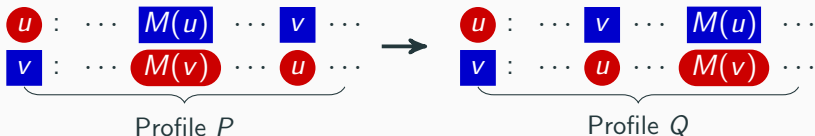
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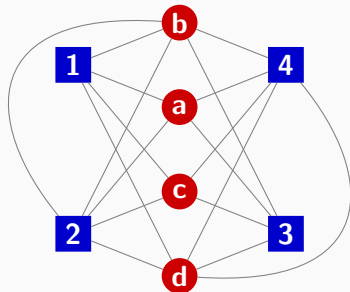
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After $O(n^4)$ -time preprocessing, testing whether two pairs together in stable matching can be done in $O(1)$ time. [Gusfield, Irving '89]. ^{7/16}

Primer on Rotations

1	:	b	c	a	d
2	:	c	d	b	a
3	:	d	a	c	b
4	:	a	b	d	c

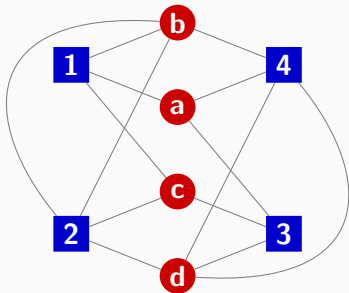
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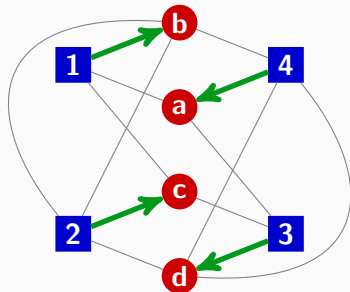
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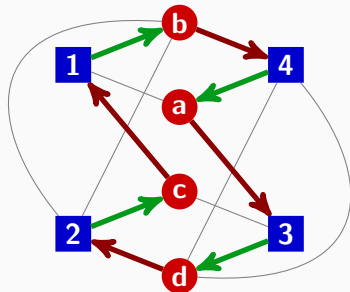
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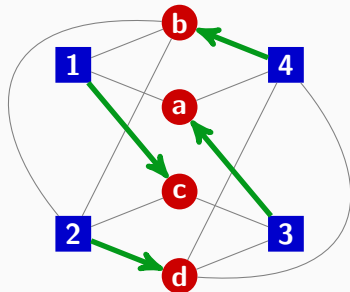
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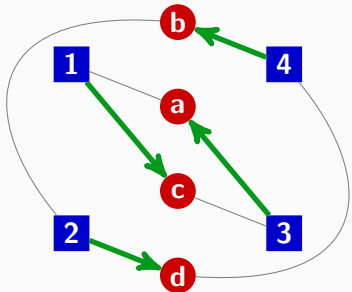
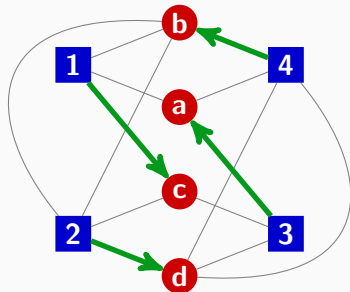
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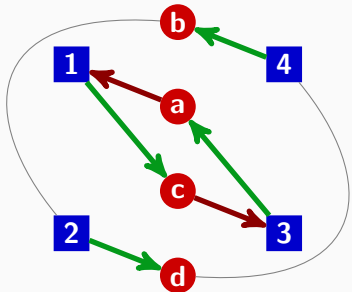
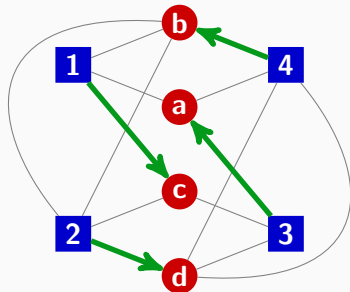
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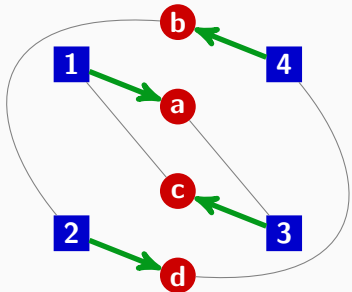
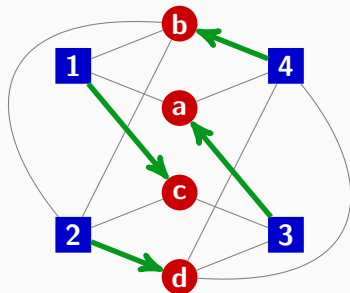
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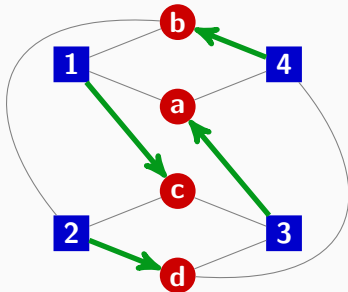
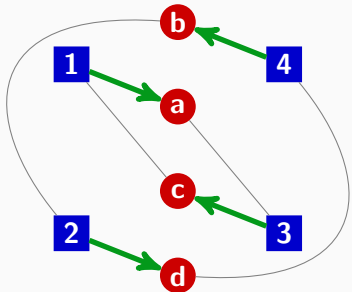
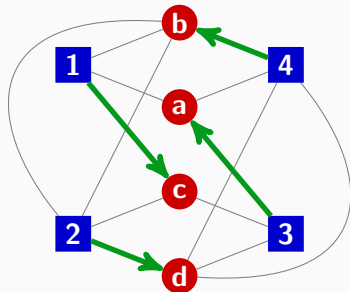
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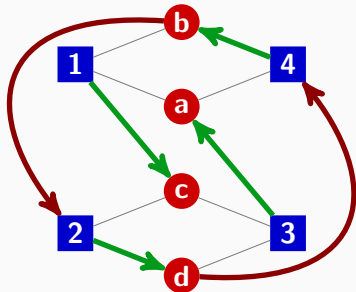
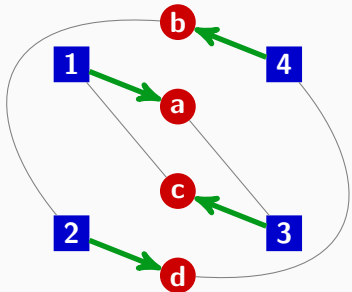
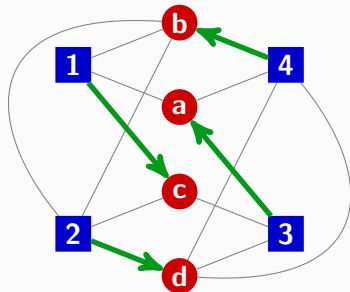
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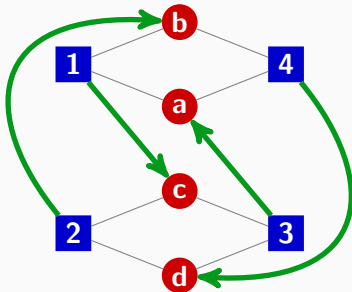
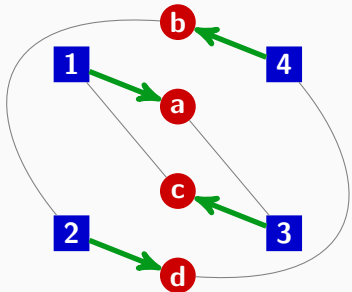
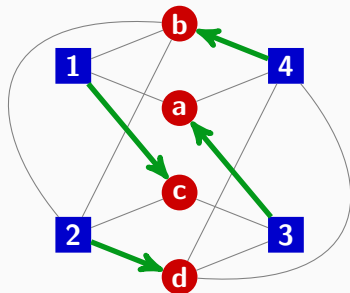
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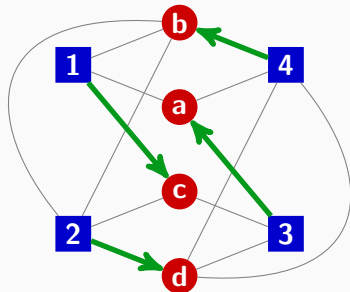
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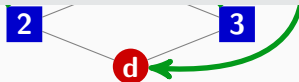
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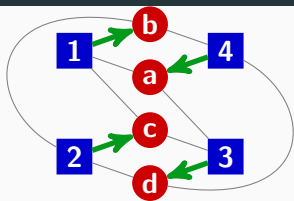


Summary

- Rotations partially ordered by order of exposure
- Rotation poset computable in $O(n^2)$ time [Gusfield, Irving '89]
- Each elimination of rotation: girls improve, boys worsen

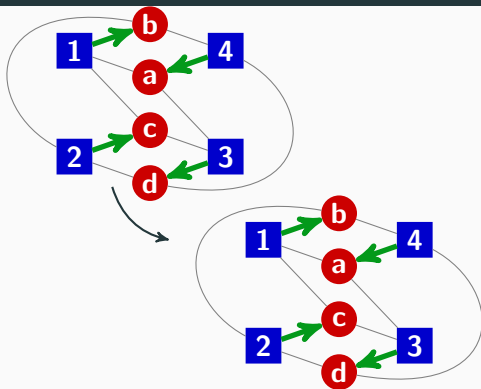


Rotation Elimination Graph



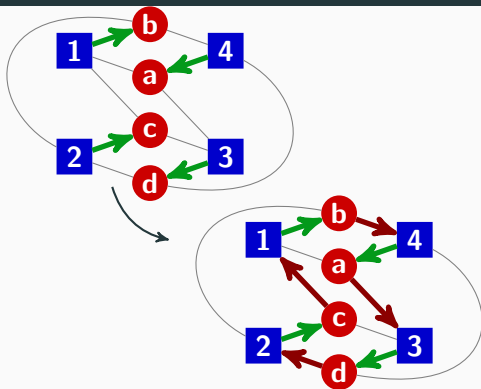
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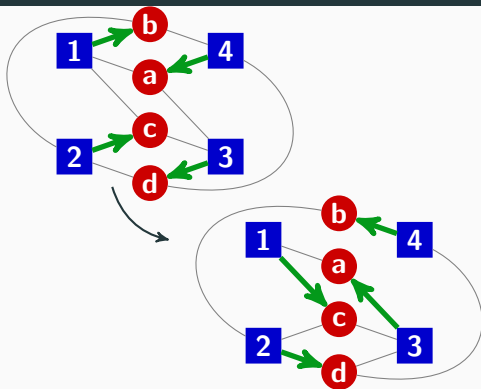
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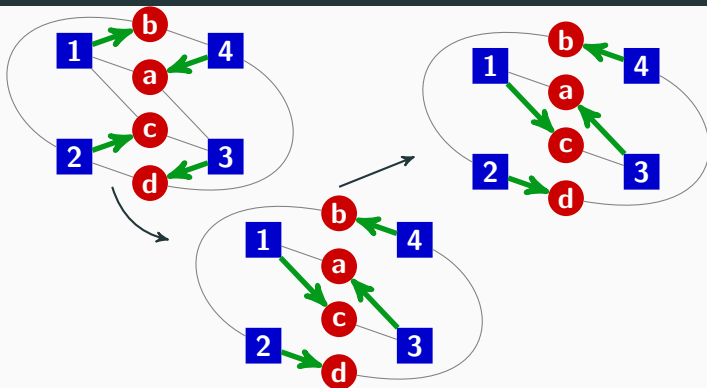
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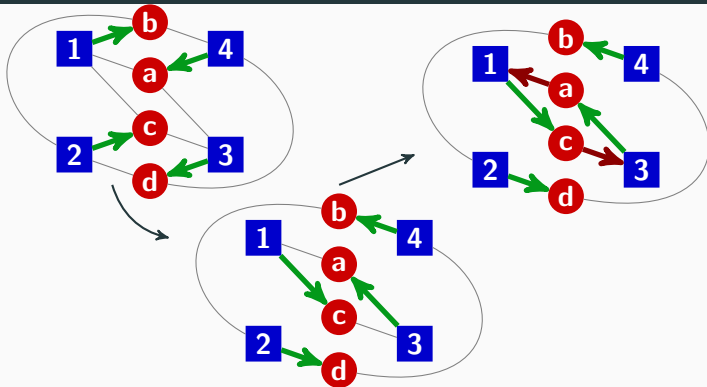
1	:	b	c	a	a	:	1	3	4
2	:	c	d	b	b	:	2	4	1
3	:	d	a	c	c	:	3	1	2
4	:	a	b	d	d	:	4	2	3

Rotation Elimination Graph



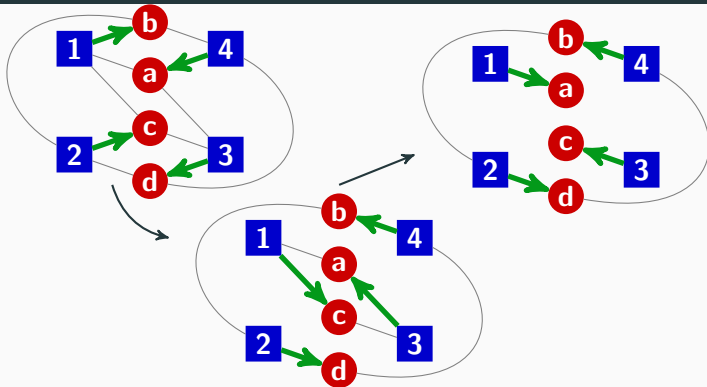
1	:	b	c	a	a	:	1	3	4
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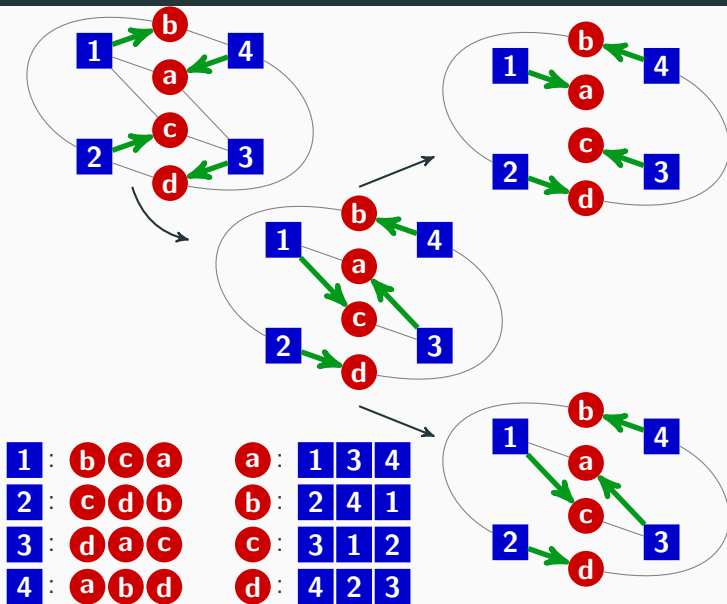
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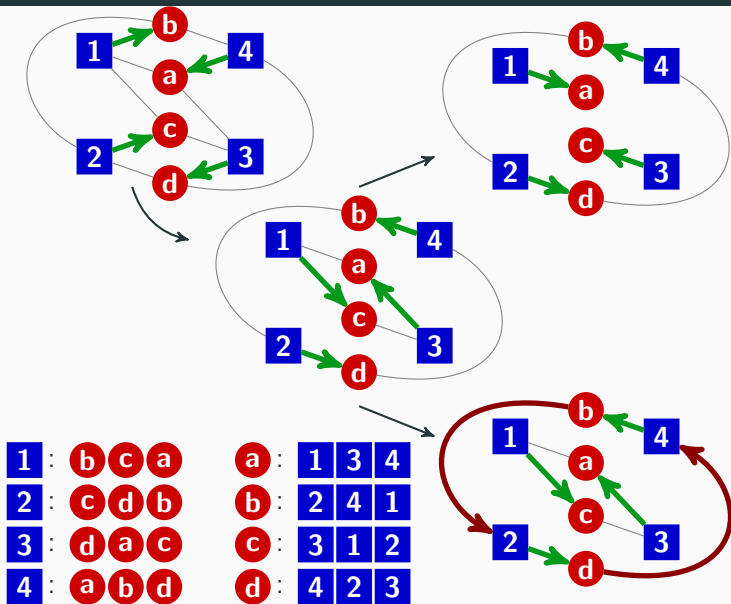


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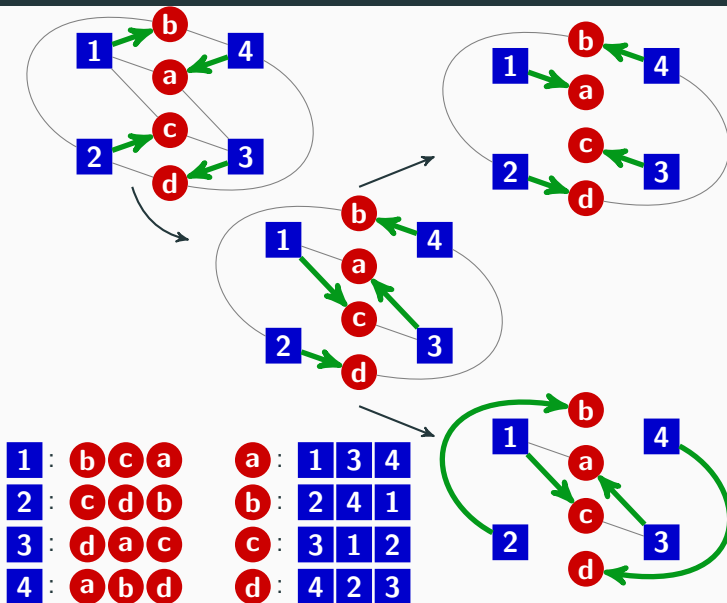
Rotation Elimination Graph



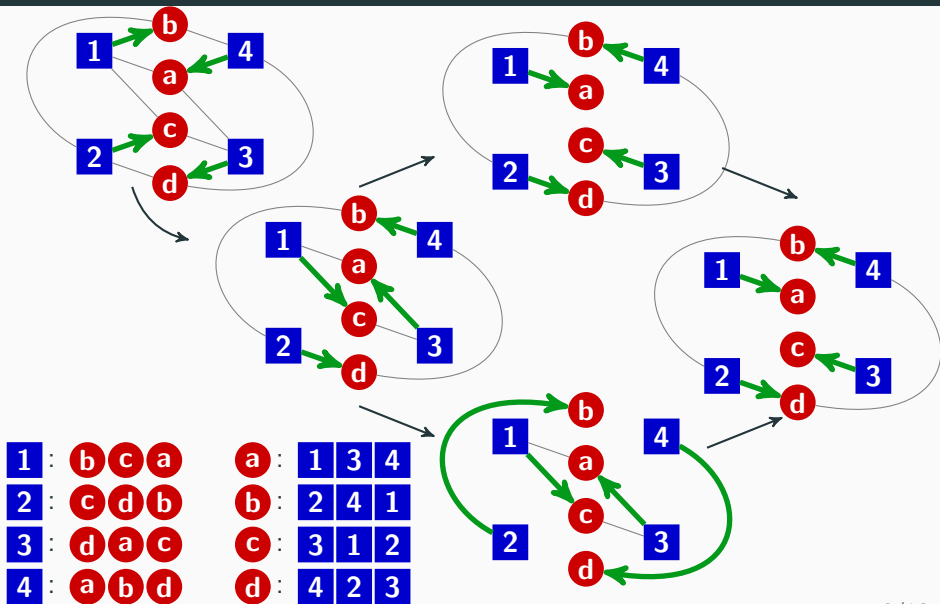
Rotation Elimination Graph



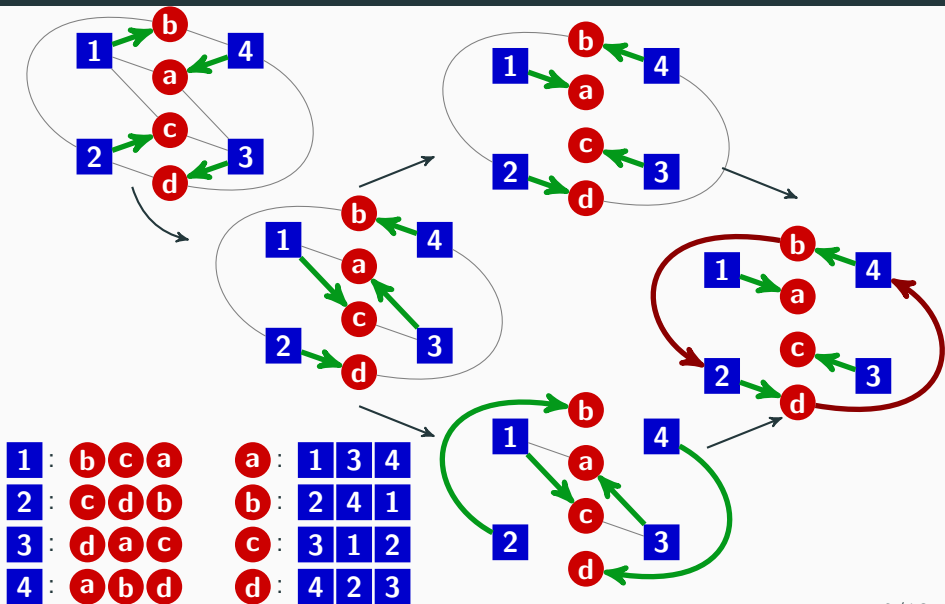
Rotation Elimination Graph



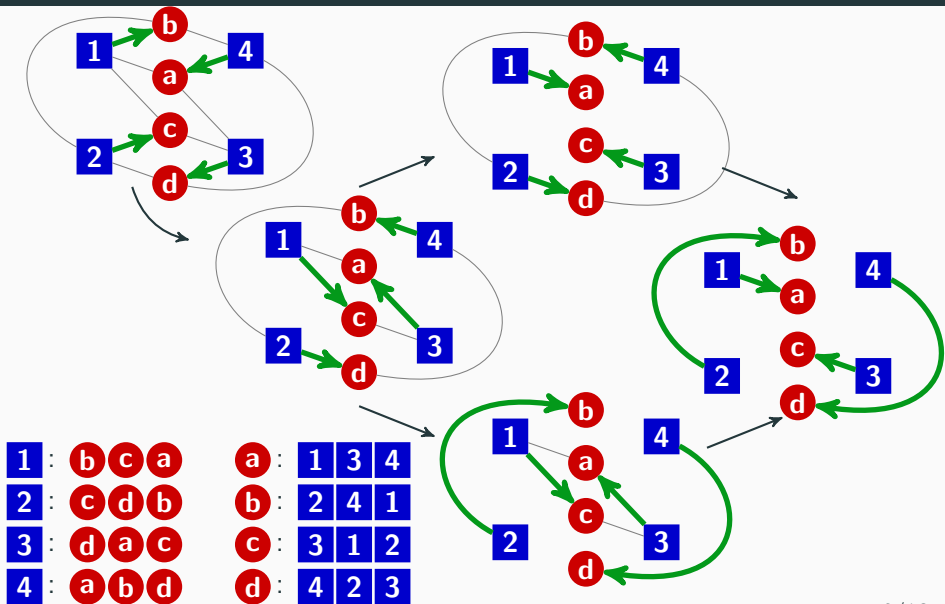
Rotation Elimination Graph



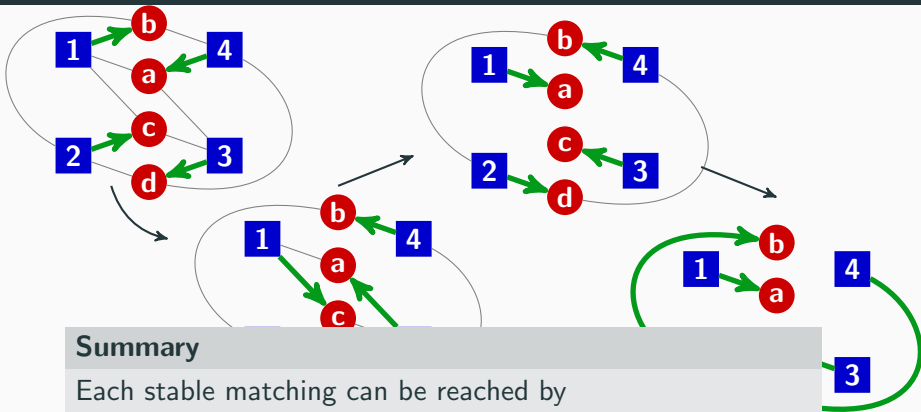
Rotation Elimination Graph



Rotation Elimination Graph



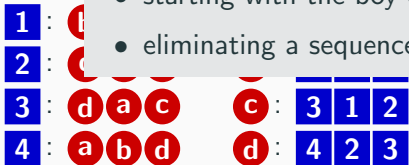
Rotation Elimination Graph



Summary

Each stable matching can be reached by

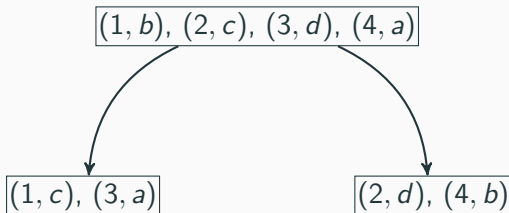
- starting with the boy-optimal stable matching, and
- eliminating a sequence of exposed rotations



Rotation Poset

1	:	b	c	a	d
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3	:	d	a	c	b
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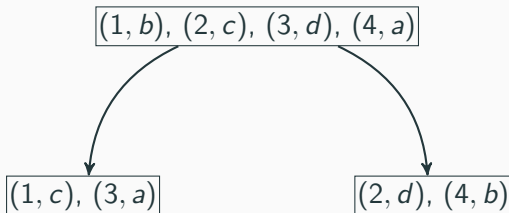
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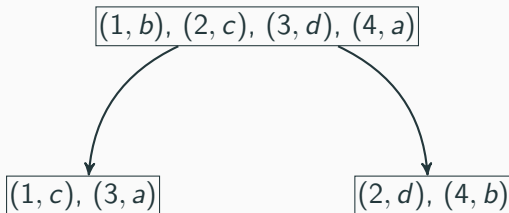


A subset S of rotations is **closed** if no arc points into S .

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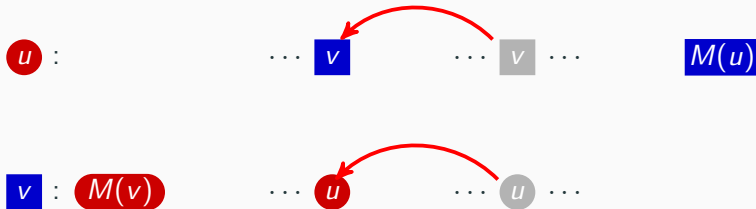
Closed subsets one-to-one correspond to stable matchings.

Rotations and Action on Critical Profiles

An arbitrary stable matching M can be obtained by

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- successively eliminate an exposed rotation.

In critical profile $R(u, v, u^*, v^*)$:

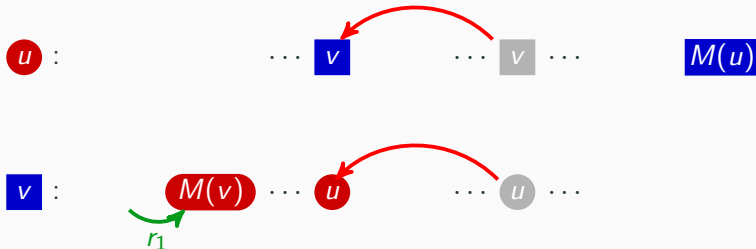


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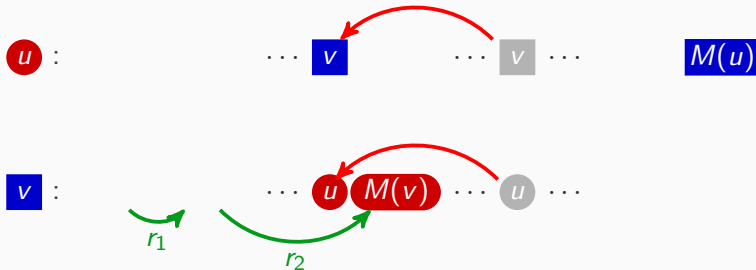


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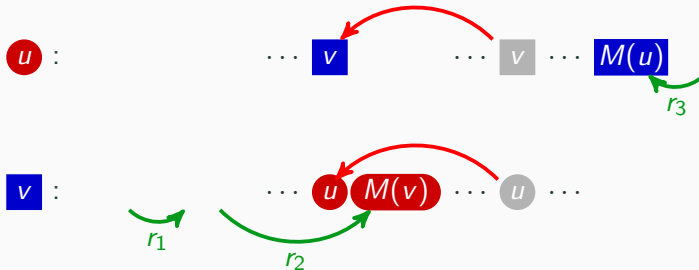


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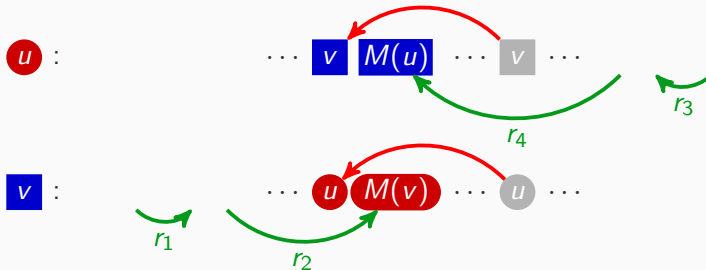


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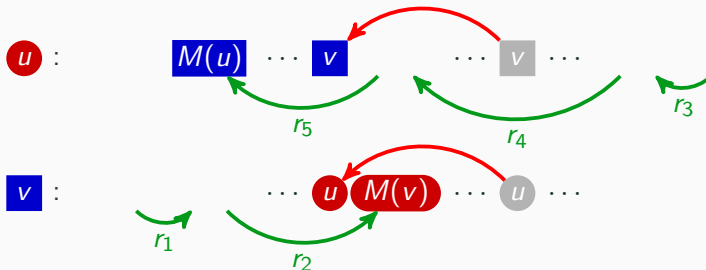


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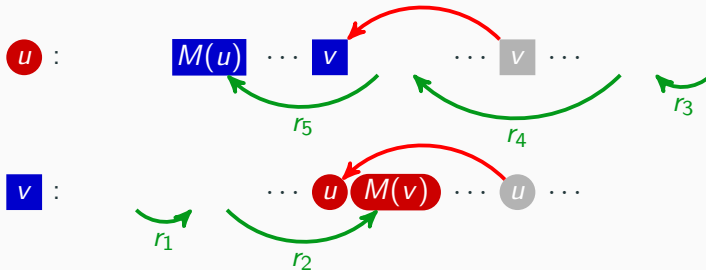


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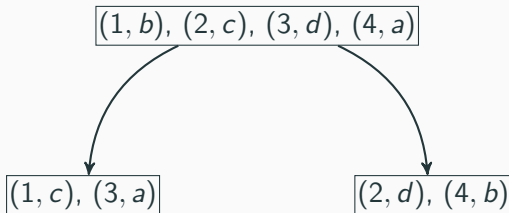


Three types of rotations: Implications, Forbidden, Necessary

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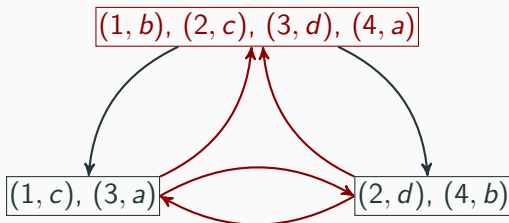
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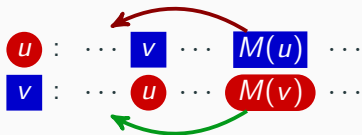
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Scenario 2: Tradeoff between distance to stability and secondary objectives.

Definition

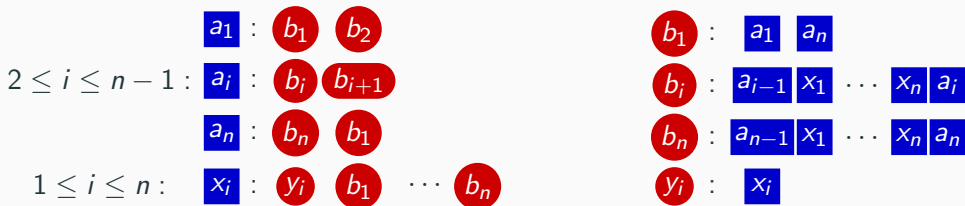
Let $d \in \mathbb{N}$. A matching M for a profile P is **globally d -nearly stable** if making at most d swaps in P makes M stable.

Definition

The **egalitarian cost** of a matching M is

$$\sum_{\{u,v\} \in M} \text{rank}_u(v) + \text{rank}_v(u).$$

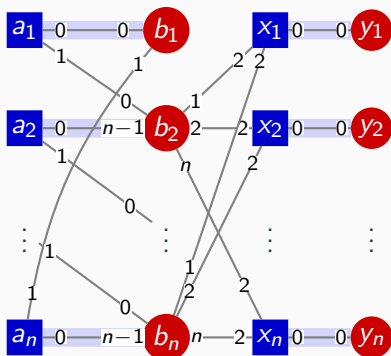
Near Stability: Example



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$$\begin{aligned}
 a_1 &: b_1 \quad b_2 \\
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 a_n &: b_n \quad b_1 \\
 1 \leq i \leq n &: x_i : y_i \quad b_1 \quad \dots \quad b_n
 \end{aligned}$$

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 \end{aligned}$$

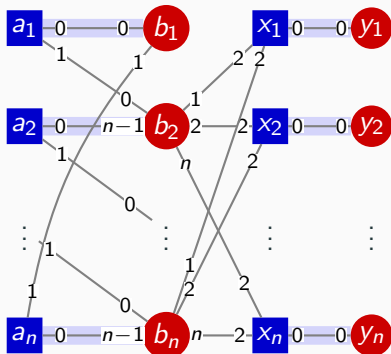


Egal. cost: $(n-1)^2$

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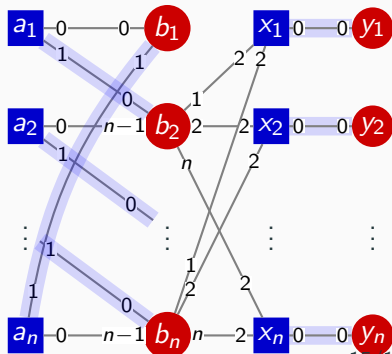
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 y_i &: x_i
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Egal. cost: $(n-1)^2$

\rightsquigarrow



Egal. cost: $n+1$, 1 bp

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Potential follow-ups:

- How robust are boy/girl-optimal matchings in real data?
- Preference restrictions \rightsquigarrow tractable cases for near stability?